

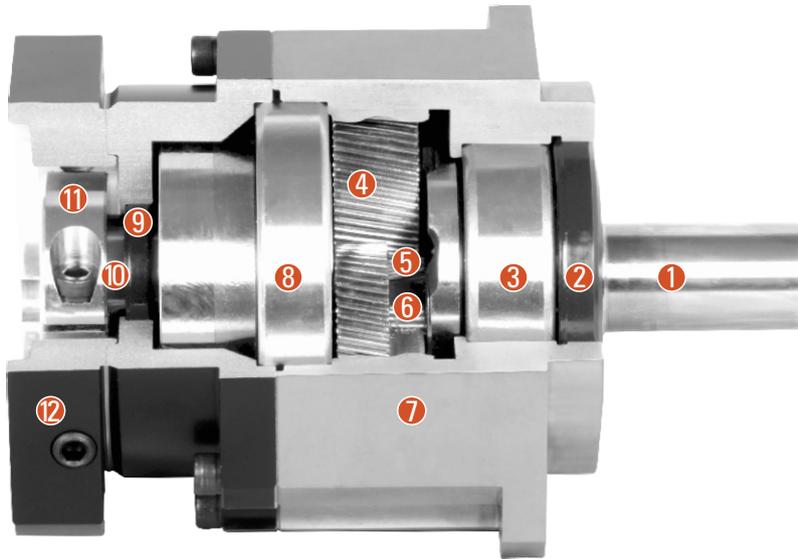


**SB/SBR/SE/SER/SD/SDR SERIES
HIGH PRECISION PLANETARY GEAR BOX**



SB SERIES GEARBOX

Sectional View



- ① Output shaft
- ② Oil seal
- ③ Output shaft front bearing
- ④ Planetary gear
- ⑤ Solar wheel
- ⑥ Full needle bearing
- ⑦ Front cover
- ⑧ Output shaft rear bearing
- ⑨ Oil seal
- ⑩ Coupling
- ⑪ Lock ring
- ⑫ Rear cover

Type and Model Number Explanation

SB Reducers				Servo Motor		
090	SB	20	()	(S1)	- 750	<input type="text"/>
①	②	③	④	⑤	⑥	⑦
① Gearbox frame size: 090 (See P04)						
② Gearbox series code: SB						
③ Gear ratio: 20, (See P04)						
④ Precision (See P04) Precision type P1, high precision type P0 Output shaft load is $\pm 5\%$ of allowable output torque						
⑤ Input shaft type S1: Locking with locking ring (Omission) (Can be used regardless whether the motor has a keyway, but "D" type is not applicable) S2: Locking with keyway (Input shaft with key) A: Other adapters (Please contact our company)						
⑥ Applicable servo motor power (W)						
⑦ Servo motor model						

PRODUCT SPECIFICATIONS

Reducer Performance Data

Specifications		Node Number	Reduction Ratio	042SB	060SB	060(A)SB	090SB	090(A)SB	115SB	142SB	180SB	220SB
Rated Output Torque T_{2N}	Nm	1	3	-	55	-	130	-	208	342	588	1140
			4	19	50	-	140	-	290	542	1050	1700
			5	22	60	-	160	-	330	650	1200	2000
			6	20	55	-	150	-	310	600	1100	1900
			7	19	50	-	140	-	300	550	1100	1800
			8	17	45	-	120	-	260	500	1000	1600
			9	14	40	-	100	-	230	450	900	1500
			10	14	40	-	100	-	230	450	900	1500
			15	-	55	55	130	130	208	342	588	1140
			20	19	50	50	140	140	290	542	1050	1700
		25	22	60	60	160	160	330	650	1200	2000	
		30	20	55	55	150	150	310	600	1100	1900	
		35	19	50	50	140	140	300	550	1100	1800	
		40	17	45	45	120	120	260	500	1000	1600	
		45	14	40	40	100	100	230	450	900	1500	
		50	22	60	60	160	160	330	650	1200	2000	
		60	20	55	55	150	150	310	600	1100	1900	
		70	19	50	50	140	140	300	550	1100	1800	
		80	17	45	45	120	120	260	500	1000	1600	
		90	14	40	40	100	100	230	450	900	1500	
100	14	40	40	100	100	230	450	900	1500			
Emergency Stop Torque T_{2NOT}^2	Nm	1,2	3 Times of Output Rated Torque									
Rated Input Speed n_{1H}	rpm	1,2	3000									
Rated Input Speed n_{1B}	rpm	1,2	6000									
Super Precision Backlash PO	arcmin	1	3~10									
		2	15~100									
Precision Backlash P1	arcmin	1	3~10									
		2	15~100									
Standard Backlash P2	arcmin	1	3~10									
		2	15~100									
Torsional Stiffness	Nm/arcmin	1,2	3~100									
Allowable Radial Force F_{2RB}^3	N	1,2	3~100									
Allowable Axial Force F_{2RB}^3	N	1,2	3~100									
Service Life	hr	1,2	3~100									
Efficiency η	%	1	3~10									
		2	15~100									
Weight	Kg	1	3~10									
		2	15~100									
Operating Temperature	°C	1,2	-10°C~+90°C									
Lubrication		1,2	Synthetic Lubricating Grease									
Protection Class		1,2	IP65									
Mounting Position		1,2	Any Direction									
Noise Level at 1m Distance ($n_1=3000rpm$, No Load)	dB(A)	1,2	3~100									

Moment of Inertia of The Reducer

Specifications		Node Number	Reduction Ratio	042SB	060SB	060(A)SB	090SB	090(A)SB	115SB	142SB	180SB	220SB
Moment Of Inertia J_1	Kg·cm ²	1	3	-	0.16	-	0.61	-	3.25	9.21	28.98	69.61
			4	0.03	0.14	-	0.48	-	2.74	7.54	23.67	54.37
			5	0.03	0.13	-	0.47	-	2.71	7.42	23.29	53.27
			6	0.03	0.13	-	0.45	-	2.65	7.25	22.75	51.72
			7	0.03	0.13	-	0.45	-	2.62	7.14	22.48	50.97
			8	0.03	0.13	-	0.44	-	2.58	7.07	22.59	50.84
			9	0.03	0.13	-	0.44	-	2.57	7.04	22.53	50.63
			10	0.03	0.13	-	0.44	-	2.57	7.03	22.51	50.56
			15	-	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
			20	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29
		25	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29	
		30	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29	
		35	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29	
		40	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29	
		45	0.03	0.03	0.13	0.13	0.47	0.47	2.71	7.42	23.29	
		50	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51	
		60	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51	
		70	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51	
		80	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51	
		90	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51	
100	0.03	0.03	0.13	0.13	0.44	0.44	2.57	7.03	22.51			

1. Gear ratio ($i=N_1/N_{out}$)

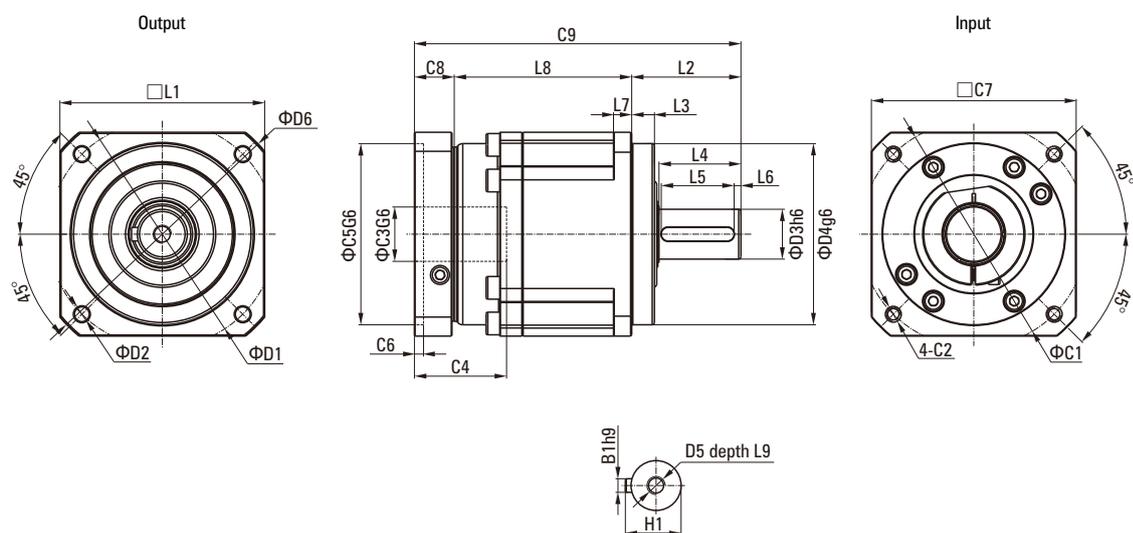
2. Maximum acceleration torque $T_{2B}=60\%$ of T_{2NOT}

3. When the output speed is 100rpm, it will act on the central position of the output shaft.

*Continuous operation, service life is 10000hrs

DIMENSIONS (SINGLE STAGE, REDUCTION RATIO $i=3\sim 10$)

Dimensional Drawing



Dimensional Table

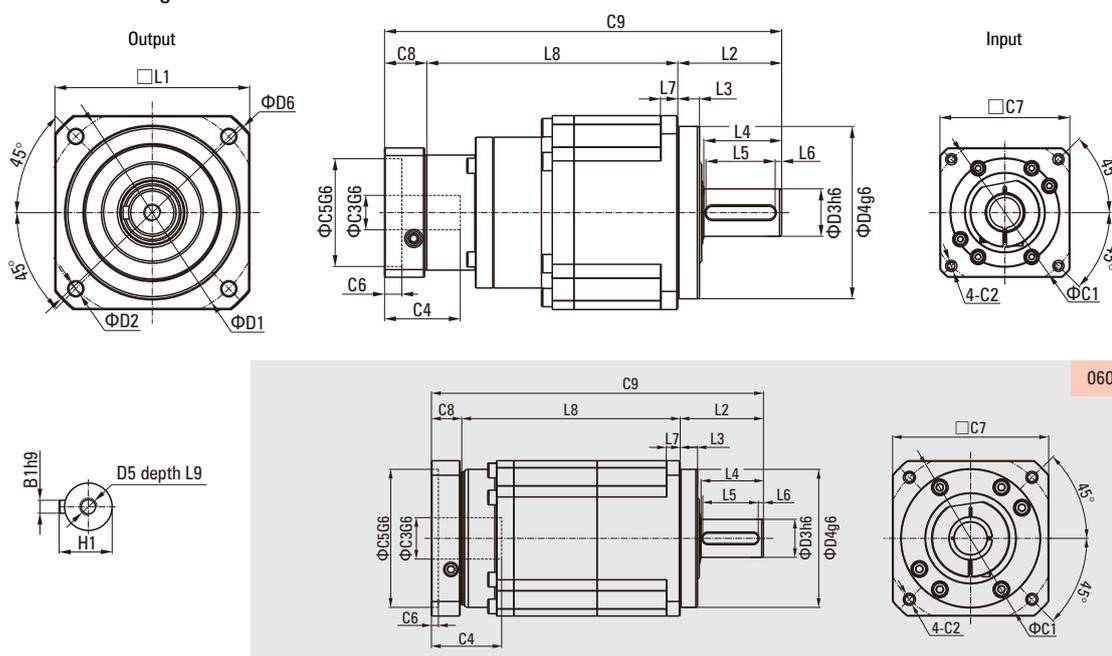
Unit: mm

Size	042SB	060SB	090SB	115SB	142SB	180SB	220SB
D1	50	70	100	130	165	215	250
D2	3.4	5.5	6.6	9	11	13	17
D3 ^{h6}	13	16	22	32	40	55	75
D4 ^{g6}	35	50	80	110	130	160	180
D5	M4×0.7P	M5×0.8P	M8×1.25P	M12×1.75P	M16×2P	M20×2.5P	M20×2.5P
D6	56	80	116	152	185	240	292
L1	42	60	90	115	142	180	220
L2	26	37	48	65	97	105	138
L3	5.5	7	10	12	15	20	30
L4	1	28	35.5	51	79	82	105
L5	16	25	32	40	70	70	90
L6	2	2	2	5	4	6	7
L7	4	6	8	10	15	20	25
L8	31	65.5	78	101.5	119.5	154	163.5
L9	4.8	12.5	19	28	36	42	42
C1	46	70	100	130	165	215	235
C2	M4×0.7P	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P	M12×1.75P
C3	*≤11/≤12	*≤14/≤16	≤19/≤24	≤32	≤35/≤38	≤42/≤48	≤55
C4	25	35	40.5	51	60	85	116
C5 ^{g6}	30	50	80	110	130	180	200
C6	3.5	8	4	5	6	6	6
C7	42	60	90	115	142	190	220
C8	29.5	19.5	17.5	20	22.5	29	63
C9	114	122	143.5	186.5	239	288	364.5
B1 ^{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5

*060SB 5,10 Reduction ratio provides C3≤16 to choose from.

DIMENSIONS (TWO STAGE, REDUCTION RATIO $i=15\sim 100$)

Dimensional Drawing



Dimensional Table

Unit: mm

Size	042SB	060(A)SB	090SB	090(A)SB	115SB	142SB	180SB	220SB
D1	50	70	100	130	165	215	250	
D2	3.4	5.5	6.6	9	11	13	17	
D3 ^{h6}	13	16	22	32	40	55	75	
D4 ^{g6}	35	50	80	110	130	160	180	
D5	M4×0.7P	M5×0.8P	M8×1.25P	M12×1.75P	M16×2P	M20×2.5P	M20×2.5P	
D6	56	80	116	152	185	240	292	
L1	42	60	90	115	142	180	220	
L2	26	37	48	65	97	105	138	
L3	5.5	7	10	12	15	20	30	
L4	1	28	36	51	79	82	105	
L5	16	25	32	40	70	70	90	
L6	2	2	3	5	4	6	7	
L7	4	6	8	10	15	20	25	
L8	58.5	102.5	116	126	143	169.5	207.5	246
L9	10	12.5	19	28	36	42	42	
C1	46	70	70	100	100	130	165	215
C2	M4×0.7P	M5×0.8P	M5×0.8P	M6×1P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P
C3	≤11/≤12	≤14/≤16	≤14/≤15.875/≤16	≤19/≤24	≤19/≤24	≤32	≤35/≤38	≤42/≤48
C4	25	35	35	40.5	40	50	60	85
C5 ^{g6}	30	50	50	80	80	110	130	180
C6	3.5	8	8	4	4	5	6	6
C7	42	60	60	90	90	115	142	190
C8	29.5	19.5	19.5	17.5	17.5	12.5	22.5	29
C9	114	159	183.5	191.5	225.5	283.5	335	409
B1 ^{h9}	5	5	6	10	12	16	20	
H1	15	18	24.5	35	43	59	79.5	

SBR SERIES GEARBOX - PRODUCT SPECIFICATIONS

Sectional View



- ① Output shaft
- ② Oil seal
- ③ Output shaft front bearing
- ④ Planetary gear
- ⑤ Solar wheel
- ⑥ Front cover
- ⑦ Output shaft rear bearing
- ⑧ Adjusting nut
- ⑨ Double row angular contact bearing
- ⑩ Output bevel gear
- ⑪ Right angle box
- ⑫ Input bevel gear
- ⑬ Lock nut
- ⑭ Input coupling
- ⑮ Locking device
- ⑯ Rear cover
- ⑰ Rear cover gasket

Reducer Performance Data

Specifications		Node Number	Reduction Ratio	060SBR	090SBR	115SBR	142SBR	180SBR	220SBR
Rated Output Torque T_{2N}	Nm	1	3	36	90	195	342	588	1140
			4	48	120	260	520	1040	1680
			5	60	150	325	650	1200	2000
			6	55	150	310	600	1100	1900
			7	50	140	300	550	1100	1800
			8	45	120	260	500	1000	1600
			9	40	100	230	450	900	1500
			10	40	100	230	450	900	1500
			14	42	140	300	550	1100	1800
			20	40	100	230	450	900	1500
		2	25	-	150	325	650	1200	2000
			30	-	150	310	600	1100	1900
			35	-	140	300	550	1100	1800
			40	-	120	260	500	1000	1600
			45	-	100	230	450	900	1500
			50	-	100	230	650	1200	2000
			60	-	150	310	600	1100	1900
			70	-	140	300	550	1100	1800
			80	-	120	260	500	1000	1600
			90	-	100	230	450	900	1500
100	-	100	230	450	900	1500			
120	-	150	310	600	1100	1900			
140	-	140	300	550	1100	1800			
160	-	120	260	550	1000	1600			
180	-	100	230	450	900	1500			
200	-	100	230	450	900	1500			
Emergency Stop Torque T_{2NOT}^2	Nm	1,2	3~200	3 Times of Output Rated Torque					
Rated Input Speed n_{1N}	rpm	1,2	3~200	3000	3000	3000	3000	3000	2000
Rated Input Speed n_{1B}	rpm	1,2	3~200	6000	6000	6000	6000	6000	4000
Super Precision Backlash P0	arcmin	1	3~20	-	≤2	≤2	≤2	≤2	≤2
		2	25~200	-	≤4	≤4	≤4	≤4	≤4
Precision Backlash P1	arcmin	1	3~20	≤4	≤4	≤4	≤4	≤4	≤4
		2	25~200	-	≤7	≤7	≤7	≤7	≤7
Standard Backlash P2	arcmin	1	3~20	≤6	≤6	≤6	≤6	≤6	≤6
		2	25~200	-	≤9	≤9	≤9	≤9	≤9
Torsional Stiffness	Nm/arcmin	1,2	3~200	7	14	25	50	145	145
Allowable Radial Force F_{2R}^3	N	1,2	3~200	1530	3250	6700	9400	14500	50000
Allowable Axial Force F_{2AB}^3	N	1,2	3~200	765	1625	3350	4700	7250	25000
Service Life	hr	1,2	3~200	20000*					
Efficiency η	%	1	3~20	≥97%					
		2	25~200	≥94%					
Weight	Kg	1	3~20	2.1	6.4	13	24.5	51	51
		2	25~200	-	7.8	14.2	27.5	54	95
Operating Temperature	°C	1,2	3~200	-10°C ~ +90°C					
Lubrication		1,2	3~200	Synthetic Lubricating Grease					
Protection Class		1,2	3~200	IP65					
Mounting Position		1,2	3~200	Any Direction					
Noise Level at 1m Distance ($n_1=3000$ rpm, No Load)	dB(A)	1,2	3~200	≤63	≤65	≤68	≤70	≤72	≤72

Moment Of Inertia Of The Reducer

Specifications		Node Number	Reduction Ratio	060SBR	090SBR	115SBR	142SBR	180SBR	220SBR
Moment Of Inertia J_r	Kg·cm ²	1	3~10	0.35	2.25	6.84	23.4	68.9	68.9
			14	0.07	1.87	6.25	21.8	65.6	65.6
			20	0.07	1.87	6.25	21.8	65.6	65.6
		2	25~100	-	0.35	6.25	21.8	65.6	65.6
120~200	-		0.31	6.25	21.8	65.6	65.6		

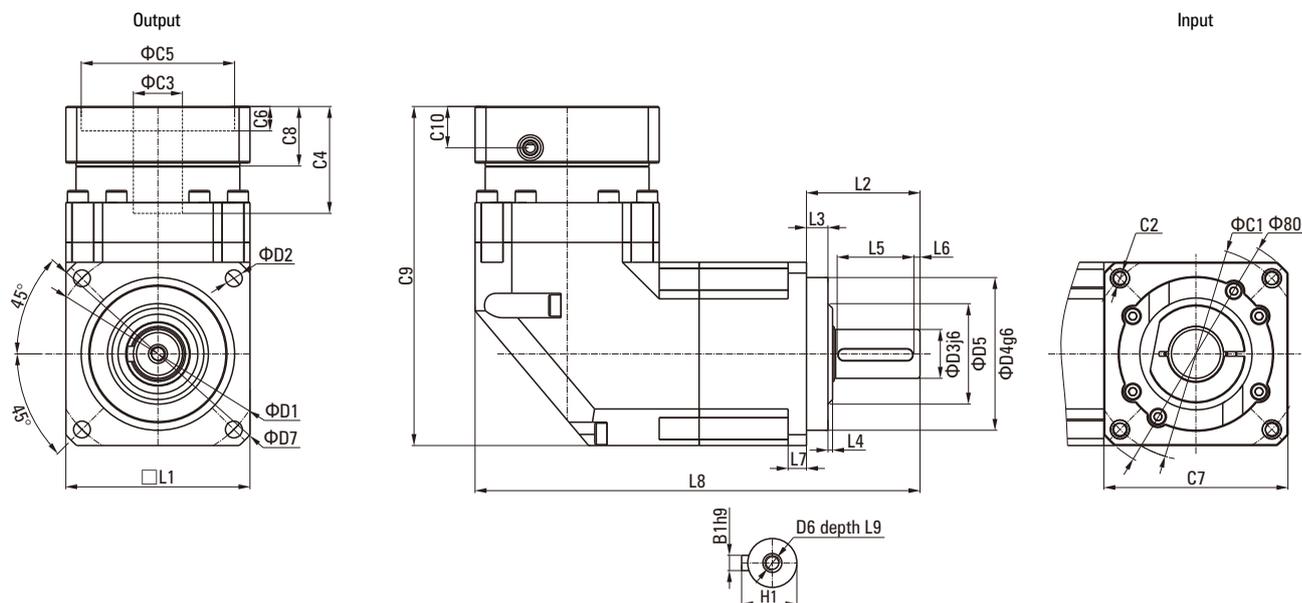
1. Gear ratio ($i = N_{in}/N_{out}$)2. Maximum acceleration torque $T_{25} = 60\%$ of T_{2NOT}

3. When the output speed is 100rpm, it will act on the central position of the output shaft.

*Continuous operation, service life is 10000hrs

DIMENSIONS (SINGLE STAGE, REDUCTION RATIO $i = 3 \sim 20$)

Dimensional Drawing



Dimensional Table

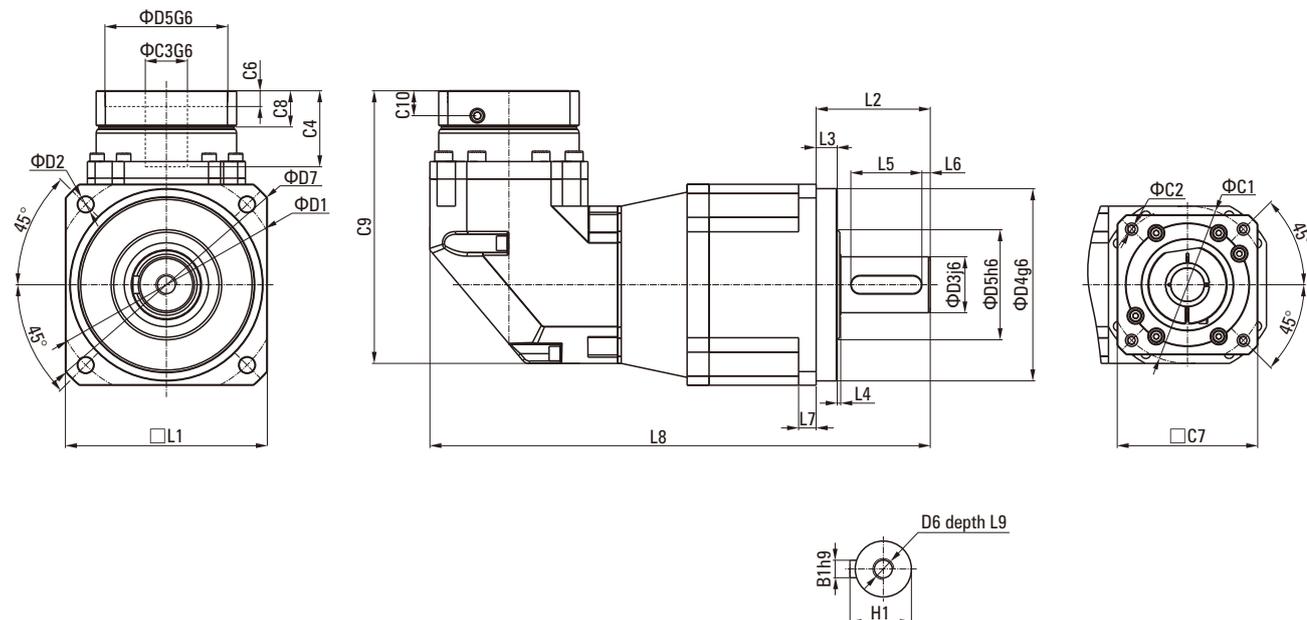
Unit: mm

Size	060SBR	090SBR	115SBR	142SBR	180SBR
D1	70	100	130	165	215
D2	5.5	6.6	9	11	13
D3 _{HS}	16	22	32	40	55
D4 _{FS}	50	80	110	130	160
D5	45	65	95	75	95
D6	M5×0.8P	M8×1.25P	M12×1.75P	M16×2P	M20×2.5P
D7	80	116	152	185	240
L1	60	90	115	142	180
L2	37	48	65	97	105
L3	7	10	12	15	20
L4	1.5	1.5	2	3	3
L5	25	32	40	63	70
L6	2	3	5	5	6
L7	6	8	10	12	15
L8	145	203	259	333	394
L9	12.5	19	28	36	42
C1 ⁴	70	100	130	165	215
C2 ⁴	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P
C3 ⁴	*≤14/≤16	≤19/≤24	≤32	≤38	≤48
C4 ⁴	30	40	50	60	85
C5 ⁴ _{FS}	50	80	110	130	180
C6 ⁴	8	4	5	6	6
C7 ⁴	60	90	115	142	190
C8 ⁴	19	17	19.5	22.5	29
C9 ⁴	111.5	152.5	191.5	235.5	303.5
C10 ⁴	13.5	10.75	13	15	20.75
B1 _{HS}	5	6	10	12	16
H1	18	24.5	35	43	59

*070SBR 5,10 Reduction ratio provides C3≤16 to choose from.

DIMENSIONS (TWO STAGE, REDUCTION RATIO $i=25\sim 200$)

Dimensional Drawing



Dimensional Table

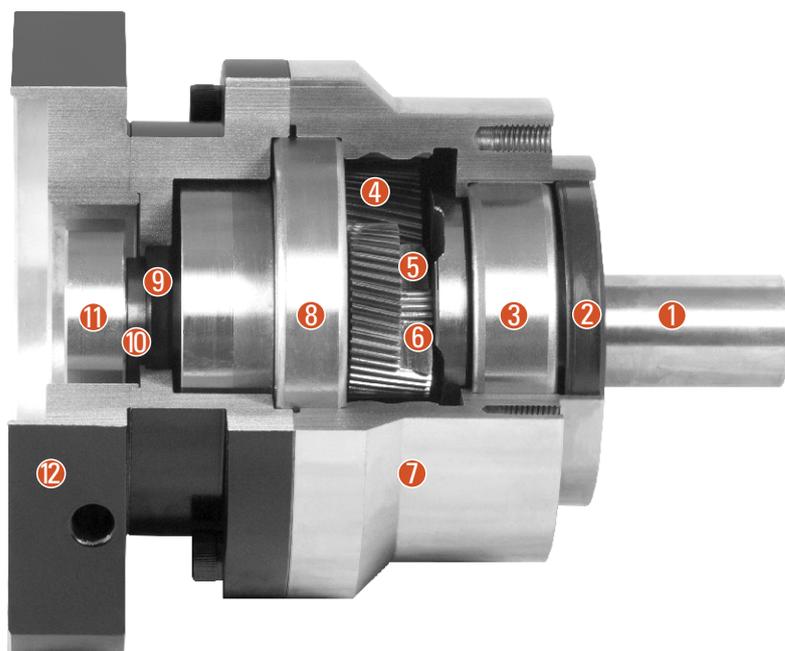
Unit: mm

Size	060(A)SBR	090SBR	115SBR	142SBR	180SBR	180SBR
D1	70	100	130	165	215	250
D2	5.5	6.6	9	11	13	17
D3 ^{h6}	16	22	32	40	55	75
D4 ^{g6}	50	80	110	130	160	180
D5	45	65	95	75	95	115
D6	M5×0.8P	M8×1.25P	M12×1.75P	M16×2P	M20×2.5P	M20×2.5P
D7	80	116	152	185	240	292
L1	60	90	115	142	180	220
L2	37	48	65	97	105	138
L3	7	10	12	15	20	30
L4	1.5	1.5	2	3	3	3
L5	25	32	40	63	70	90
L6	2	3	5	5	6	7
L7	6	8	10	12	15	20
L8	170	206.5	285	365	394	521
L9	12.5	19	28	36	42	42
C1	70	70	100	130	165	215
C2	M5×0.8P	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P
C3 ^{g6}	≤14/≤16	≤14/≤16	≤19/≤24	≤32	≤38	≤48
C4	34	34	40	50	60	85
C5 ^{g6}	50	50	80	110	130	180
C6	8	8	4	5	6	6
C7	60	60	90	115	142	190
C8	19	19	17	19.5	22.5	29
C9	111	126.5	165	205	254.5	323.5
C10	13.5	13.5	10.75	13	15	20.75
B1 ^{h9}	5	6	10	12	16	20
H1	18	24.5	35	43	59	79.5

*070SBR 5,10 Reduction ratio provides C3≤16 to choose from.

SE SERIES GEARBOX

Sectional View



- ① Output shaft
- ② Oil seal
- ③ Output shaft front bearing
- ④ Planetary gear
- ⑤ Solar wheel
- ⑥ Full needle bearing
- ⑦ Front cover
- ⑧ Output shaft rear bearing
- ⑨ Oil seal
- ⑩ Coupling
- ⑪ Lock ring
- ⑫ Rear cover

Type and Model Number

SE Reducers				Servo Motor			
090	SE	20	()	(S1)	-	750	<input type="text"/>
①	②	③	④	⑤	⑥	⑦	
① Gearbox frame size: 090 (See P10)							
② Gearbox series code: ZE							
③ Gear Ratio: 20 (See P10)							
④ Precision (See P10) Standard type P2 (Omission), precision type P1, high precision type P0 Precision (Output shaft load is $\pm 5\%$ of allowable output torque)							
⑤ Input shaft type S1: Locking with locking ring (Omission) (Can be used regardless whether the motor has a keyway, but "D" type is not applicable) S2: Locking with keyway (Input shaft with key) A: Other adapters (Please contact our company)							
⑥ Applicable servo motor power (W)							
⑦ Servo motor model							

PRODUCT SPECIFICATIONS

Reducer Performance Data

Specifications	Node Number	Reduction Ratio	050SE	070SE	090SE	120SE	155SE	205SE	235SE	
Rated Output Torque T_{2N}	Nm	1	3	-	55	130	208	342	588	1140
			4	19	50	140	290	542	1050	1700
			5	22	60	160	330	650	1200	2000
			6	20	55	150	310	600	1100	1900
			7	19	50	140	300	550	1100	1800
			8	17	45	120	260	500	1000	1600
			9	14	40	100	230	450	900	1500
			10	14	40	100	230	450	900	1500
			15	-	55	130	208	342	588	1140
			20	19	50	140	290	542	1050	1700
	25	22	60	160	330	650	1200	2000		
	30	20	55	150	310	600	1100	1900		
	35	19	50	140	300	550	1100	1800		
	40	17	45	120	260	500	1000	1600		
	45	14	40	100	230	450	900	1500		
	50	22	60	160	330	650	1200	2000		
	60	20	55	150	310	600	1100	1900		
	70	19	50	140	300	550	1100	1800		
	80	17	45	120	260	500	1000	1600		
	90	14	40	100	230	450	900	1500		
100	14	40	100	230	450	900	1500			
Emergency Stop Torque T_{2NOT}^2	Nm	1,2	3 Times of Output Rated Torque							
Rated Input Speed n_{1N}	rpm	1,2	3000							
Rated Input Speed n_{1B}	rpm	1,2	6000							
Super Precision Backlash P0	arcmin	1	3~10							
		2	15~100							
Precision Backlash P1	arcmin	1	3~10							
		2	15~100							
Standard Backlash P2	arcmin	1	3~10							
		2	15~100							
Torsional Stiffness	Nm/arcmin	1,2	3~100							
Allowable Radial Force F_{2R}^3	N	1,2	3~100							
Allowable Axial Force F_{2AB}^3	N	1,2	3~100							
Service Life	hr	1,2	3~100							
Efficiency η	%	1	20000*							
		2	3~10							
Weight	Kg	1	≥97%							
		2	15~100							
Operating Temperature	°C	1,2	-10°C~+90°C							
Lubrication		1,2	Synthetic Lubricating Grease							
Protection Class		1,2	IP65							
Mounting Position		1,2	Any Direction							
Noise Level at 1m Distance ($n_1=3000$ rpm, No Load)	dB(A)	1,2	3~100							

Moment of Inertia of The Reducer

Specifications	Node Number	Reduction Ratio	050SE	070SE	090SE	120SE	155SE	205SE	235SE	
Moment Of Inertia J_1	Kg-cm ²	1	3	-	0.16	0.61	3.25	9.21	28.98	69.61
			4	0.03	0.14	0.48	2.74	7.54	23.67	54.37
			5	0.03	0.13	0.47	2.71	7.42	23.29	53.27
			6	0.03	0.13	0.45	2.65	7.25	22.75	51.72
			7	0.03	0.13	0.45	2.62	7.14	22.48	50.97
			8	0.03	0.13	0.44	2.58	7.07	22.59	50.84
			9	0.03	0.13	0.44	2.57	7.04	22.53	50.63
			10	0.03	0.13	0.44	2.57	7.03	22.51	50.56
			15	-	0.03	0.13	0.47	2.71	7.42	23.29
			20	0.03	0.03	0.13	0.47	2.71	7.42	23.29
	25	0.03	0.03	0.13	0.47	2.71	7.42	23.29		
	30	0.03	0.03	0.13	0.47	2.71	7.42	23.29		
	35	0.03	0.03	0.13	0.47	2.71	7.42	23.29		
	40	0.03	0.03	0.13	0.47	2.71	7.42	23.29		
	45	0.03	0.03	0.13	0.47	2.71	7.42	23.29		
	50	0.03	0.03	0.13	0.44	2.57	7.03	22.51		
	60	0.03	0.03	0.13	0.44	2.57	7.03	22.51		
	70	0.03	0.03	0.13	0.44	2.57	7.03	22.51		
	80	0.03	0.03	0.13	0.44	2.57	7.03	22.51		
	90	0.03	0.03	0.13	0.44	2.57	7.03	22.51		
100	0.03	0.03	0.13	0.44	2.57	7.03	22.51			

1.Gear ratio($i=N_1/N_{out}$)

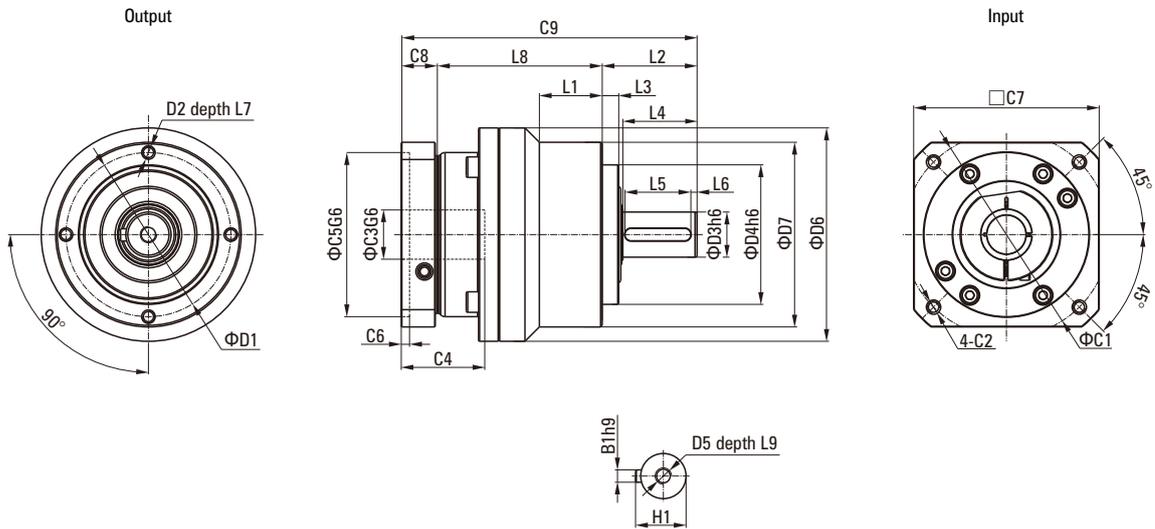
2.Maximum acceleration torque $T_{2B}=60\%$ of T_{2NOT}

3.When the output speed is 100rpm, it will act on the central position of the output shaft.

*Continuous operation, service life is 10000hrs

DIMENSIONS (SINGLE STAGE, REDUCTION RATIO $i=3\sim 10$)

Dimensional Drawing



Dimensional Table

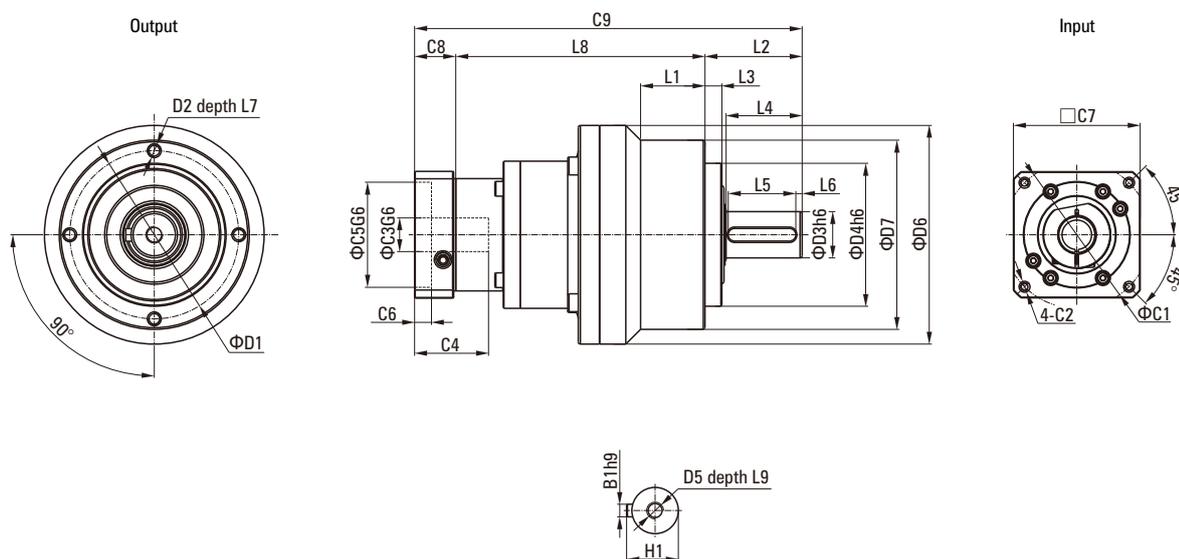
Unit: mm

Size	050SE	070SE	090SE	120SE	155SE	205SE
D1	44	62	80	108	140	184
D2	M5×0.7P	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P
D3 ^{h6}	12	16	22	32	40	55
D4 ^{g6}	35	52	68	90	120	160
D5	M4×0.7P	M5×0.8P	M8×1.25P	M12×1.75P	M16×2P	M20×2.5P
D6	53	70	104	130	162	205
D7	50	70	90	120	155	205
L1	-	-	31.5	36	50	-
L2	24.5	36	46	70	97	100
L3	4	6	8	17	15	15
L4	1	28	36	51	79	82
L5	14	25	32	40	70	70
L6	2	2	3	5	4	6
L7	8	10	12	16	20	22
L8	47	66.5	80	96.5	119.5	154
L9	4.5	12.5	19	28	36	42
C1	10	70	100	130	165	215
C2	M4×0.7P	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P
C3	*≤11/≤12	*≤14/≤16	≤19/≤24	≤32	≤35/≤38	≤42/≤48
C4	30	35	40.5	51	60	85
C5 ^{g6}	30	50	80	110	130	180
C6	3.5	8	4	5	6	6
C7	48	60	90	115	142	190
C8	19.5	19.5	17.5	20	22.5	29
C9	91	117	143.5	186.5	239	288
B1 ^{h9}	4	5	6	10	12	16
H1	14	18	24.5	35	43	59

*070SE 5, 10 Reduction ratio provides C3 ≤ 16 to choose from.

DIMENSIONS (TWO STAGE, REDUCTION RATIO $i=15\sim 100$)

Dimensional Drawing



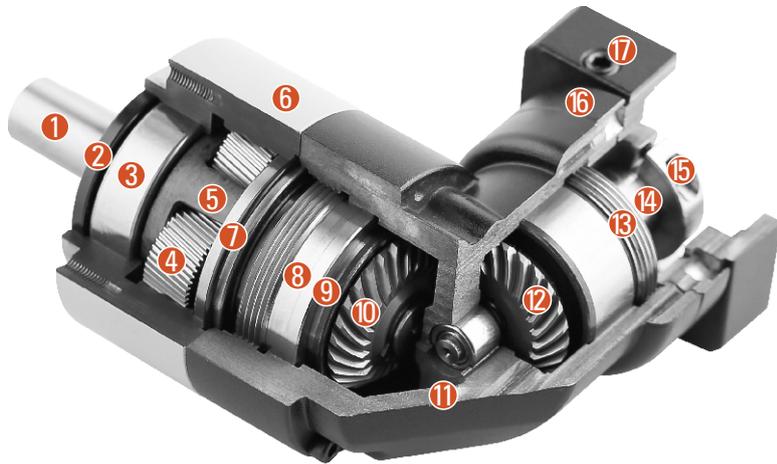
Dimensional Table

Unit: mm

Size	050SE	070SE	090SE	120SE	155SE	205SE
D1	44	62	80	108	140	184
D2	M4×0.7P	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P
D3 ^{h6}	12	16	22	32	40	55
D4 ^{g6}	35	52	68	90	120	160
D5	M4×0.7P	M5×0.8P	M8×1.25P	M12×1.75P	M16×2P	M20×2.5P
D6	53	70	104	130	162	205
D7	50	70	90	120	155	205
L1	-	-	31.5	36	50	-
L2	24.5	36	46	70	97	100
L3	4	6.5	8	17	15	15
L4	1	1	36	51	79	82
L5	14	25	32	40	63	70
L6	2	2	3	5	5	6
L7	8	10	12	16	20	22
L8	74	87.8	118	138	169.5	207.5
L9	4.5	4.8	19	28	36	42
C1	46	46	70	100	130	165
C2	M4×0.7P	M4×0.7P	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P
C3	≤11/≤12	≤11/≤12	≤14/≤15.875/≤16	≤19/≤24	≤32	≤35/≤38
C4	30	30	35	40.5	50	60
C5 ^{g6}	30	30	50	80	110	130
C6	3.5	3.5	8	4	5	6
C7	48	48	60	90	115	142
C8	19.5	19.5	19.5	17.5	12.5	22.5
C9	118	143	183.5	225.5	283.5	335
B1 ^{h9}	4	5	6	10	12	16
H1	14	18	24.5	35	43	59

SER SERIES GEARBOX - PRODUCT SPECIFICATIONS

Sectional View



- ① Output shaft
- ② Oil seal
- ③ Output shaft front bearing
- ④ Planetary gear
- ⑤ Solar wheel
- ⑥ Front cover
- ⑦ Output shaft rear bearing
- ⑧ Adjusting nut
- ⑨ Double row angular contact bearing
- ⑩ Output bevel gear
- ⑪ Right angle box
- ⑫ Input bevel gear
- ⑬ Lock nut
- ⑭ Input coupling
- ⑮ Locking device
- ⑯ Rear cover
- ⑰ Rear cover gasket

Reducer Performance Data

Specifications		Node Number	Reduction Ratio	070SER	090SER	120SER	155SER
Rated Output Torque T_{2N}	Nm	1	3	36	90	195	342
			4	48	120	260	520
			5	60	150	325	650
			6	55	150	310	600
			7	50	140	300	550
			8	45	120	260	500
			9	40	100	230	450
			10	40	100	230	450
			14	42	140	300	550
			20	40	100	230	450
		2	25	-	150	325	650
			30	-	150	310	600
			35	-	140	300	550
			40	-	120	260	500
			45	-	100	230	450
			50	-	100	230	650
			60	-	150	310	600
			70	-	140	300	550
			80	-	120	260	500
			90	-	100	230	450
100	-	100	230	450			
120	-	150	310	600			
140	-	140	300	550			
160	-	120	260	550			
180	-	100	230	450			
200	-	100	230	450			
Emergency Stop Torque T_{2NCT}^2	Nm	1,2	3~200	3 Times of Output Rated Torque			
Rated Input Speed n_{1H}	rpm	1,2	3~200	3000	3000	3000	3000
Rated Input Speed n_{1B}	rpm	1,2	3~200	6000	6000	6000	6000
Super Precision Backlash P0	arcmin	1	3~20	-	≤2	≤2	≤2
		2	25~200	-	≤4	≤4	≤4
Precision Backlash P1	arcmin	1	3~20	≤4	≤4	≤4	≤4
		2	25~200	-	≤7	≤7	≤7
Standard Backlash P2	arcmin	1	3~20	≤6	≤6	≤6	≤6
		2	25~200	-	≤9	≤9	≤9
Torsional Stiffness	Nm/arcmin	1,2	3~200	7	14	25	50
Allowable Radial Force F_{2R}^3	N	1,2	3~200	1530	3250	6700	9400
Allowable Axial Force F_{2aB}^3	N	1,2	3~200	765	1625	3350	4700
Service Life	hr	1,2	3~200	20000*			
Efficiency η	%	1	3~20	≥97%			
		2	25~200	≥94%			
Weight	Kg	1	3~20	2.1	6.4	13	24.5
		2	25~200	-	7.8	14.2	27.5
Operating Temperature	°C	1,2	3~200	-10°C~+90°C			
Lubrication		1,2	3~200	Synthetic Lubricating Grease			
Protection Class		1,2	3~200	IP65			
Mounting Position		1,2	3~200	Any Direction			
Noise Level at 1m Distance ($n_1=3000\text{rpm}$, No Load)	dB(A)	1,2	3~200	≤63	≤65	≤68	≤70

Moment Of Inertia Of The Reducer

Specifications		Node Number	Reduction Ratio	060SBR	090SBR	115SBR	142SBR
Moment Of Inertia J_1	Kg-cm ²	1	3~10	0.35	2.25	6.84	23.4
			14	0.07	1.87	6.25	21.8
			20	0.07	1.87	6.25	21.8
		2	25~100	0.09	0.35	2.25	6.84
120~200	-		0.31	1.87	6.25		

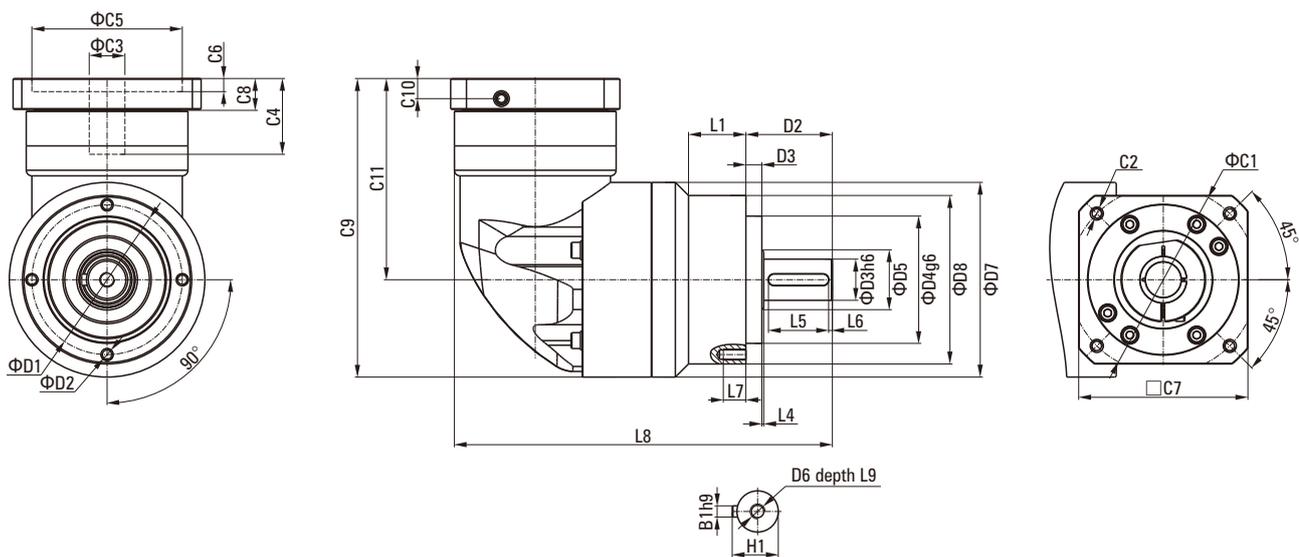
1. Gear ratio ($i=N_{in}/N_{out}$)2. Maximum acceleration torque $T_{z8}=60\%$ of T_{2N0T}

3. When the output speed is 100rpm, it will act on the central position of the output shaft.

*Continuous operation, service life is 10000hrs

DIMENSIONS (SINGLE STAGE, REDUCTION RATIO $i=3\sim 20$)

Dimensional Drawing



Dimensional Table

Unit: mm

Size	070SER	090SER	120SER	155SER
D1	62	80	108	140
D2	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P
D3 _{h6}	16	22	32	40
D4 _{g6}	52	68	90	120
D5	22	30	40	75
D6	M5×0.8P	M8×1.25P	M12×1.75P	M16×2P
D7	70	104	130	162
D8	70	90	120	155
L1	-	33.5	38	50
L2	36	46	70	97
L3	6.5	8.5	17.5	15
L4	1	1	1.5	3
L5	25	32	40	63
L6	2	3	5	5
L7	10	12	16	20
L8	146	201	252	324.5
L9	12.5	19	28	36
C1	70	100	130	165
C2	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P
C3	≤14/≤16	≤19/≤24	≤32	≤38
C4	34	40	50	60
C5	50	80	110	130
C6	8	4	5	6
C7	60	90	115	142
C8	19	17	19.5	22.5
C9	116.5	159.5	199	254.5
C10	13.5	10.75	13	15
C11	81.5	107.5	134	164.5
B1 _{h9}	5	6	10	12
H1	18	24.5	35	43

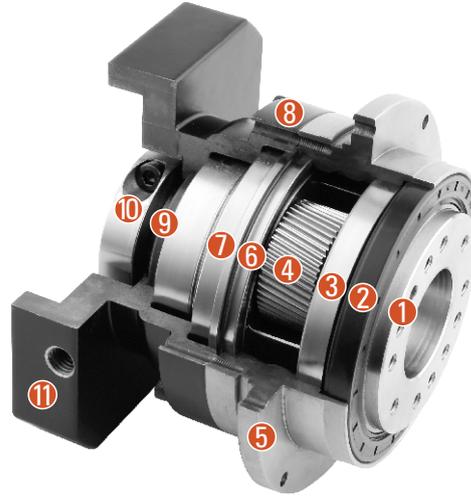
*070SBR 5,10 Reduction ratio provides $C3 \leq 16$ to choose from.

SD SERIES GEARBOX - PRODUCT SPECIFICATIONS

Sectional View

- ① Output shaft
- ② Oil seal
- ③ Output shaft front bearing
- ④ Planetary gear
- ⑤ Flange inner tooth
- ⑥ Output shaft rear bearing

- ⑦ Lock nut
- ⑧ Rear cover
- ⑨ Solar wheel
- ⑩ Locking device
- ⑪ Rear cover gasket



Reducer Performance Data

Specifications	Node Number	Reduction Ratio	SD064	SD090	SD110	SD140	SD200	
Rated Output Torque T_{2N}	1	4	48	-	-	560	1100	
		5	60	160	330	650	1200	
		7	50	140	300	550	1100	
		10	40	100	230	450	900	
	2	20	48	-	-	560	1100	
		25	60	160	330	650	1200	
		35	50	140	300	550	1100	
		40	48	130	270	560	1100	
		50	60	160	330	650	1200	
		70	50	140	300	550	1100	
	100	40	100	230	450	900		
	Emergency Stop Torque T_{2NOT}^2	Nm	1,2	3 Times of Output Rated Torque				
	Rated Input Speed n_{1N}	rpm	1,2	4~100	3000	3000	3000	3000
	Rated Input Speed n_{1B}	rpm	1,2	4~100	6000	6000	6000	6000
Super Precision Backlash P0	arcmin	1	4~10	-	≤1	≤1	≤1	
		2	15~100	-	≤3	≤3	≤3	
Precision Backlash P1	arcmin	1	4~10	≤3	≤3	≤3	≤3	
		2	15~100	≤5	≤5	≤5	≤5	
Standard Backlash P2	arcmin	1	4~10	≤5	≤5	≤5	≤5	
		2	15~100	≤7	≤7	≤7	≤7	
Torsional Stiffness	Nm/arcmin	1,2	4~100	13	31	82	151	
Maximum bending moment M_{2B}^3	Nm	1,2	4~100	125	235	430	1300	
Allowable Radial Force F_{2B}^3	N	1,2	4~100	1050	2850	2990	10590	
Service Life	hr	1,2	4~100	20000*				
Efficiency η	%	1	4~10	≥97%				
		2	15~100	≥94%				
Weight	Kg	1	4~10	1.2	3.0	5.6	11.9	
		2	15~100	1.6	3.7	7.3	15.9	
Operating Temperature	°C	1,2	4~100	-10°C~+90°C				
Lubrication		1,2	4~100	Synthetic Lubricating Grease (NYOGEL 792D)				
Protection Class		1,2	4~100	IP65				
Mounting Position		1,2	4~100	Any Direction				
Noise Level at 1m Distance ($n_1=3000$ rpm, No Load)	dB(A)	1,2	4~100	≤58	≤60	≤63	≤65	

Moment Of Inertia Of The Reducer

Specifications	Node Number	Reduction Ratio	SD064	SD090	SD110	SD140	SD200
Moment Of Inertia J_1	1	4	0.14	-	-	7.54	25.03
		5	0.13	0.47	2.71	7.42	23.29
		7	0.13	0.45	2.62	7.14	22.48
		10	0.13	0.44	2.57	7.03	22.51
	2	20	0.03	-	-	2.71	7.42
		25	0.03	0.13	0.47	2.71	7.42
		35	0.03	0.13	0.47	2.71	7.42
		40	0.03	0.13	0.44	2.57	7.03
		50	0.03	0.13	0.44	2.57	7.03
		70	0.03	0.13	0.44	2.57	7.03
	100	0.03	0.13	0.44	2.57	7.03	

1. Gear ratio ($i=N_1/N_{out}$)

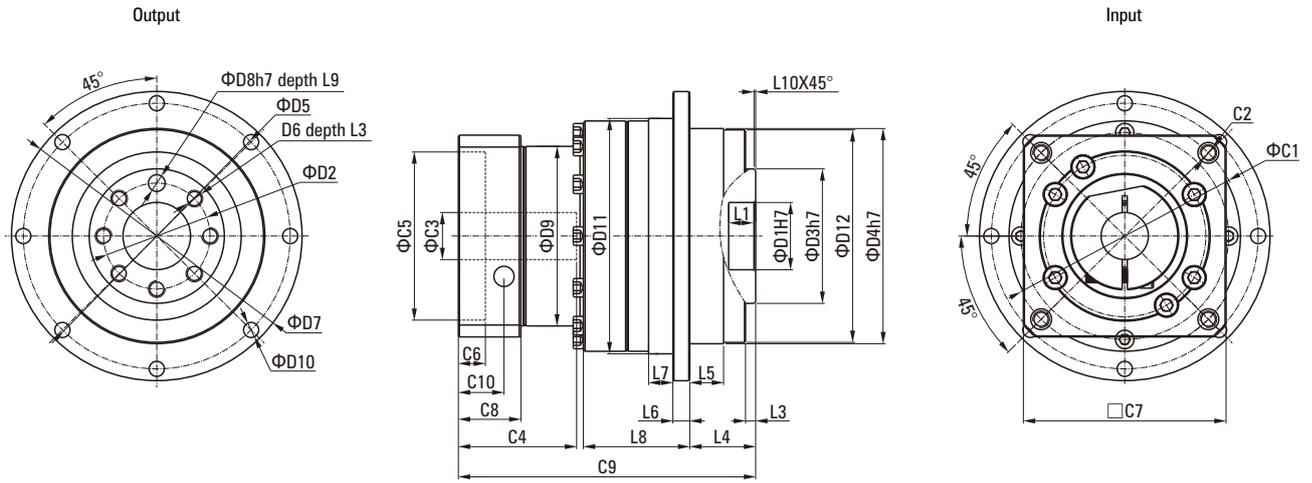
2. Maximum acceleration torque $T_{2B}=60\%$ of T_{2NOT}

3. When the output speed is 100rpm, it will act on the central position of the output shaft.

*Continuous operation, service life is 10000hrs

DIMENSIONS (SINGLE STAGE, REDUCTION RATIO $i=4\sim 10$)

Dimensional Drawing



Dimensional Table

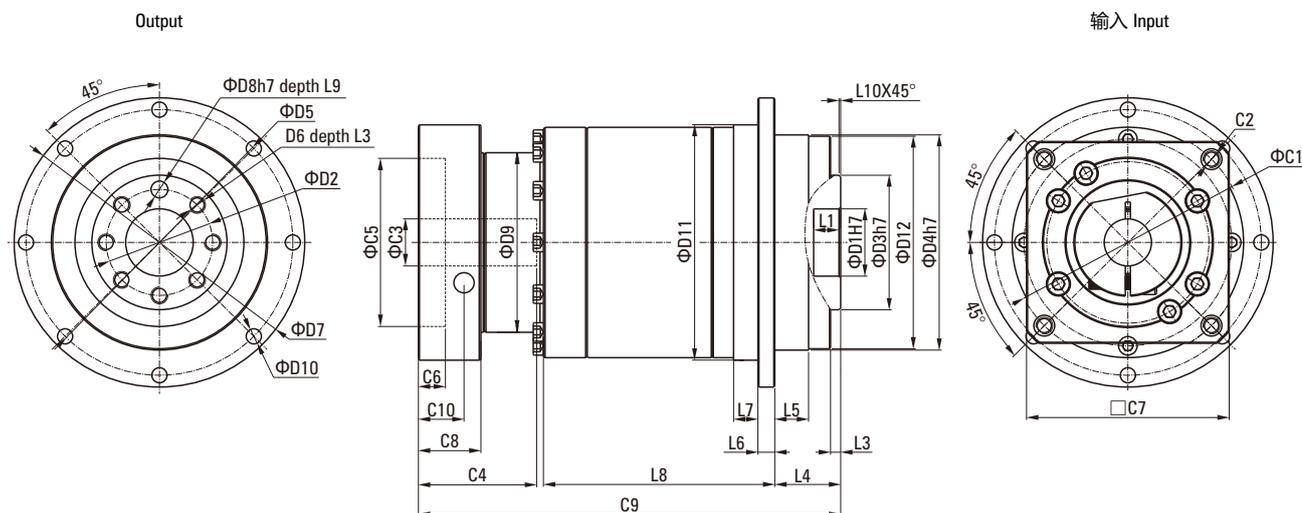
Unit: mm

Size	SD064	SD090	SD110	SD140	SD200
D1 _{h7}	20	31.5	40	50	80
D2	31.5	50	63	80	125
D3 _{h7}	40	63	80	100	160
D4 _{h7}	64	90	110	140	200
D5	79	109	135	168	233
D6	7×M5×0.8P	7×M6×1P	11×M6×1P	11×M8×1.25P	11×M10×1.5P
D7	86	118	145	179	247
D8 _{h7}	5	6	6	8	10
D9	55	77	90	113	138
D10	8×4.5	8×5.5	8×5.5	12×6.6	12×9
D11 _{h7}	70	95	120	152	212
D12	63.2	89.2	109.2	139.2	199.2
L1	8	12	12	12	16
L2	8	13.5	13.5	17	22.5
L3	3	6	6	9	8
L4	19.5	30	29	38	50
L5	7	10	10	14.6	15
L6	4	7	8	10	12
L7	7.7	8	10	12	15
L8	28.5	27	37	62	69.5
L9	6	7	7	7	10
L10	0.5	1	1	1	1
C1 [†]	70	100	130	165	215
C2 [†]	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P
C3 [†]	*≤14/≤16	≤19/≤24	≤32	≤38	≤48
C4 [†]	34	40	50	60	85
C5 [†] ₀₆	50	80	110	130	180
C6 [†]	8	4	5	9	6
C7 [†]	60	90	115	142	190
C8 [†]	19	17	19.5	22.5	29
C9 [†]	82.5	99.5	121.5	151	199.5
C10 [†]	13.5	10.75	13	15	20.75
OD	66×2	90×3	110×3	145×3	200×5

*060SD 5,10 Reduction ratio provides C3≤16 to choose from.

DIMENSIONS (TWO STAGE, REDUCTION RATIO $i=20\sim 100$)

Dimensional Drawing



Dimensional Table

Unit: mm

Size	SD064	SD090	SD110	SD140	SD200
D1 _{h7}	20	31.5	40	50	80
D2	31.5	50	63	80	125
D3 _{h7}	40	63	80	100	160
D4 _{h7}	64	90	110	140	200
D5	79	109	135	168	233
D6	7×M5×0.8P	7×M6×1P	11×M6×1P	11×M8×1.25P	11×M10×1.5P
D7	86	118	145	179	247
D8 _{h7}	5	6	6	8	10
D9	45.5	53.4	77	102	125
D10	8×4.5	8×5.5	8×5.5	12×6.6	12×9
D11 _{h7}	70	95	120	152	212
D12	63.2	89.2	109.2	139.2	199.2
L1	8	12	12	12	16
L2	8	13.5	13.5	17	22.5
L3	3	6	6	6	8
L4	19.5	30	29	38	50
L5	7	10	10	14.6	15
L6	4	7	8	10	12
L7	7.7	8	10	12	15
L8	65	60	87.5	110	132.5
L9	6	7	7	7	10
L10	0.5	1	1	1	1
C1 ⁵	46	70	100	130	165
C2 ⁵	M4×0.7P	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P
C3 ⁵	*≤11/≤12	≤14/≤15.875/≤16	≤19/≤24	≤32	≤38
C4 ⁵	30	34	40	50	60
C5 ⁵ _{GS}	30	50	80	110	130
C6 ⁵	3.5	8	4	5	6
C7 ⁵	48	60	90	115	142
C8 ⁵	19.5	19	17	19.5	22.5
C9 ⁵	108	134	160	204	248
C10 ⁵	13.25	13.5	10.75	13	15
OD	66×2	90×3	110×3	145×3	200×5

*060SD 5,10 Reduction ratio provides C3≤16 to choose from.

SDR SERIES GEARBOX - PRODUCT SPECIFICATIONS

Sectional View



- ① Output shaft
- ② Oil seal
- ③ Output shaft front bearing
- ④ Planetary gear
- ⑤ Front cover
- ⑥ Output shaft rear bearing
- ⑦ Solar wheel
- ⑧ Adjusting nut
- ⑨ Double row angular contact bearing
- ⑩ Output bevel gear
- ⑪ Right angle box
- ⑫ Input bevel gear
- ⑬ Lock nut
- ⑭ Input coupling
- ⑮ Locking device
- ⑯ Rear cover
- ⑰ Rear cover gasket

Reducer Performance Data

Specifications		Node Number	Reduction Ratio	064SDR	090SDR	110SDR	140SDR	200SDR
Rated Output Torque T_{2N}	Nm	1	4	48	-	-	560	1100
			5	60	160	330	650	1200
			7	50	140	300	550	1100
			10	40	100	230	450	900
			14	42	140	300	550	1100
			20	40	100	230	450	900
		2	25	60	160	330	650	1200
			35	50	140	300	550	1100
			40	48	-	-	560	1100
			50	60	160	330	650	1200
			70	50	140	300	550	1100
			100	40	100	230	450	900
			140	-	140	300	550	1100
			200	-	100	230	450	900
Emergency Stop Torque T_{2NCT}^2	Nm	1,2	3~200	3 Times of Output Rated Torque				
Rated Input Speed n_{1H}	rpm	1,2	3~200	3000	3000	3000	3000	3000
Rated Input Speed n_{1B}	rpm	1,2	3~200	6000	6000	6000	6000	6000
Super Precision Backlash P0	arcmin	1	3~20	-	≤2	≤2	≤2	≤2
		2	25~200	-	≤4	≤4	≤4	≤4
Precision Backlash P1	arcmin	1	3~20	≤4	≤4	≤4	≤4	≤4
		2	25~200	-	≤7	≤7	≤7	≤7
Standard Backlash P2	arcmin	1	3~20	≤6	≤6	≤6	≤6	≤6
		2	25~200	-	≤9	≤9	≤9	≤9
Torsional Stiffness	Nm/arcmin	1,2	3~200	13	31	82	151	440
Maximum bending moment M_{2KB}^3	Nm	1,2	3~200	120	235	430	1300	3064
Allowable Axial Force F_{2aB}^3	N	1,2	3~200	1050	2850	2990	10590	16660
Service Life	hr	1,2	3~200	20000 ⁴				
Efficiency η	%	1	3~20	≥95%				
		2	25~200	≥92%				
Weight	Kg	1	3~20	2.1	5.9	10.5	21.9	50.9
		2	25~200	1.9	4.5	9.8	20.1	45.4
Operating Temperature	°C	1,2	3~200	-10°C ~ +90°C				
Lubrication		1,2	3~200	Synthetic Lubricating Grease				
Protection Class		1,2	3~200	IP65				
Mounting Position		1,2	3~200	Any Direction				
Noise Level at 1m Distance ($n_1=3000\text{rpm}$, No Load)	dB(A)	1,2	3~200	≤63	≤65	≤68	≤70	≤72

减速机转动惯量 Moment Of Inertia Of The Reducer

Specifications		Node Number	Reduction Ratio	064SDR	090SDR	110SDR	140SDR	200SDR
Moment Of Inertia J_1	Kg-cm ²	1	4~10	0.35	2.25	6.84	23.4	68.9
			14	0.07	1.87	6.25	21.8	65.6
			20	0.07	1.87	6.25	21.8	65.6
		2	25~100	0.09	0.35	2.25	6.84	23.4
			140~200	-	0.31	1.87	6.25	21.8

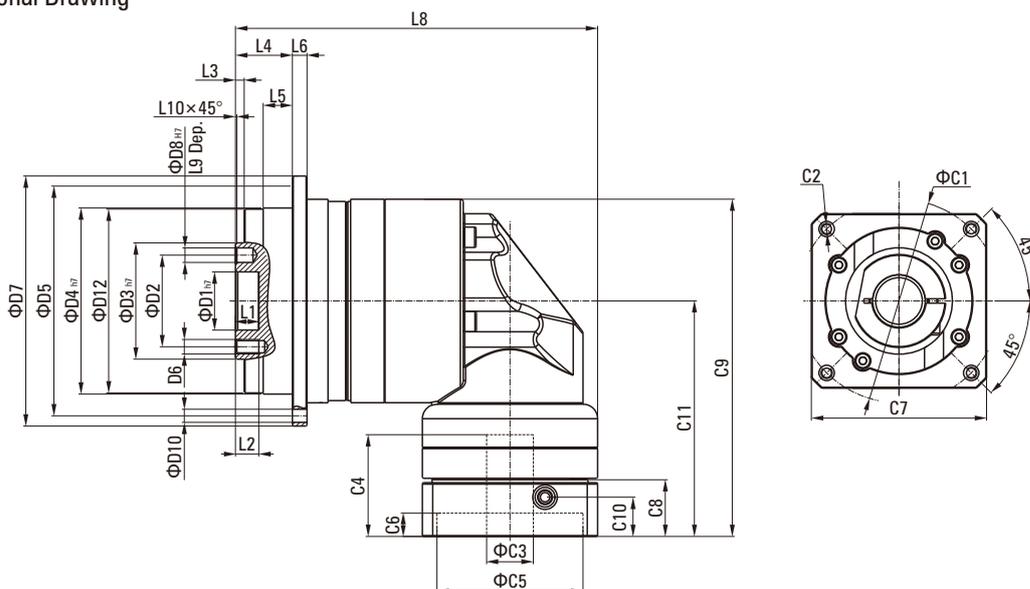
1. Gear ratio ($i = N_p / N_{out}$)2. Maximum acceleration torque $T_{26} = 60\%$ of T_{2N0T}

3. When the output speed is 100rpm, it will act on the central position of the output shaft.

*Continuous operation, service life is 10000hrs

DIMENSIONS (SINGLE STAGE, REDUCTION RATIO $i = 3 \sim 20$)

Dimensional Drawing



Dimensional Table

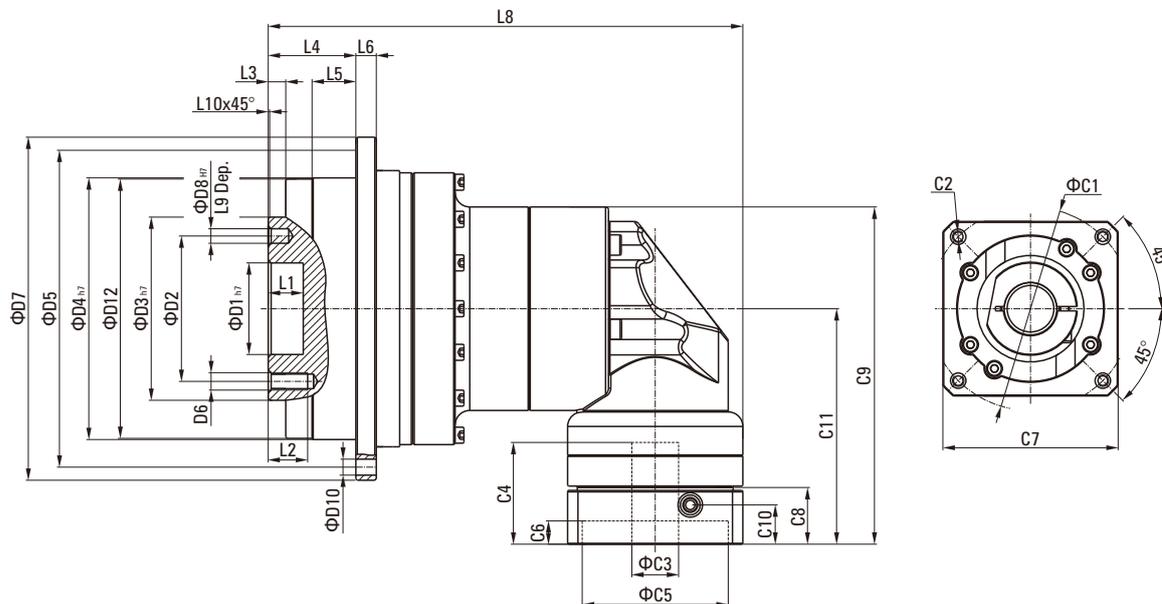
Unit: mm

Size	064SDR	090SDR	110SDR	140SDR	200SDR
D1 _{H7}	20	31.5	40	50	80
D2	31.5	50	63	80	125
D3 _{H7}	40	63	80	100	160
D4 _{H7}	54	80	110	140	200
D5	79	109	135	168	233
D6	7×M5×0.8P	7×M6×1P	11×M6×1P	11×M8×1.25P	11×M10×1.5P
D7	86	118	145	179	247
D8 _{H7}	5	6	6	8	10
D10	8×4.5	8×5.5	8×5.5	12×6.6	12×9
D12	63.2	89.2	109.2	139.2	199.2
L1	8	12	12	12	16
L2	8	13.5	13.5	17	22.5
L3	3	6	6	6	8
L4	19.5	30	29	38	50
L5	7	10	10	14.6	15
L6	4	7	8	10	12
L8	126	172.5	201	263.5	334.5
L9	6	7	7	7	10
L10	0.5	1	1	1	1
C1	70	100	130	165	215
C2	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P	M12×1.75P
C3	≤14/≤16	≤19/≤24	≤32	≤38	≤48
C4	34	40	50	60	85
C5	50	80	110	130	180
C6	8	4	5	6	6
C7	60	90	115	142	190
C8	19	17	19.5	22.5	29
C9	116.5	159.5	199	254.5	316
C10	13.5	10.75	13	15	20.75
C11	81.5	107.5	134	164.5	213.5

*070SBR 5,10 Reduction ratio provides C3≤16 to choose from.

DIMENSIONS (TWO STAGE, REDUCTION RATIO $i=25\sim 200$)

Dimensional Drawing



Dimensional Table

Unit: mm

Size	064SDR	090SDR	110SDR	140SDR	200SDR
D1 _{h7}	20	31.5	40	50	80
D2	31.5	50	63	80	125
D3 _{h7}	40	63	80	100	160
D4 _{h7}	54	80	110	140	200
D5	79	109	135	168	233
D6	7×M5×0.8P	7×M6×1P	11×M6×1P	11×M8×1.25P	11×M10×1.5P
D7	86	118	145	179	247
D8 _{h7}	5	6	6	8	10
D10	8×4.5	8×5.5	8×5.5	12×6.6	12×9
D12	63.2	89.2	109.2	139.2	199.2
L1	8	12	12	12	16
L2	8	13.5	13.5	17	22.5
L3	3	6	6	6	8
L4	19.5	30	29	38	50
L5	7	10	10	14.6	15
L6	4	7	8	10	12
L8	132.5	163	217.5	269.5	333.5
L9	6	7	7	7	10
L10	0.5	1	1	1	1
C1	46	70	100	130	165
C2	M4×0.7P	M5×0.8P	M6×1P	M8×1.25P	M10×1.5P
C3	≤11/≤12	≤14/≤16	≤19/≤24	≤32	≤38
C4	30	34	40	50	60
C5	30	50	80	110	130
C6	3.5	8	4	5	6
C7	48	60	90	115	142
C8	19.5	19	17	19.5	22.5
C9	108.25	128.25	166.5	209	269.5
C10	13.25	13.5	10.75	13	15
C11	74	81.5	107.5	134	164.5

*070SBR 5,10 Reduction ratio provides C3≤16 to choose from.

ASSEMBLY

Assembly Procedure

If a customer personally assembles the servo motor and reducer please use the following tip. The reducer flange to which the servo motor is attached has different dimensions based on the motor specified. Therefore, assembly may be impossible for some motor. Make sure the correct motor is specified before ordering the reducer.

1. Spec. In Case Of Assembling A Motor Without Key

- ① Take off the rubber cap, turn the input shaft, and match the head of the bolt to the hole of the rubber cap. Make sure that the set bolt is loosened.
- ② Gradually put the motor shaft into the input shaft (Ensure that it is smoothly put in without iam.) Be careful not to be inserted with the motor tilted.
- ③ Attach the motor to the reducer and fasten the bolt with designated fastening torque. (See table 1)
- ④ Fasten the set bolt of the input shaft with designated fastening torque wrench, etc. (See table 2)
- ⑤ Put on a rubber cap. It is the end of assembling.

● Table1

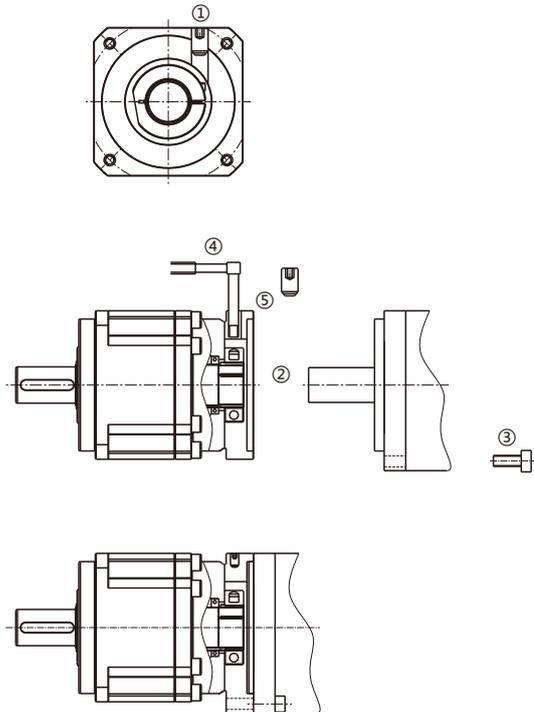
Motor Combination Bolt	Fastening Torque	
	(N·m)	(kgf·cm)
M3	1.0	10
M4	3.0	30
M5	5.8	60
M6	9.8	100
M8	19.6	200
M10	39.2	400
M12	68.6	700
M16	168	1650

● Table2

Combination Bolt	Fastening Torque	
	(N·m)	(kgf·cm)
M3	1.5	15
M4	3.5	35
M5	7.1	71
M6	12	120
M8	30	300
M10	60	612

You can assemble the motor with keyway like above when take off the key.
There is no risk of dislocation.

● SB/SE Series Schematic Diagram



ASSEMBLY

Reducer Assembly

Jointing with reducer In case of jointing a reducer with the device, make sure that the combining side is plane without inconsistency, and when assemble reducer outo equipment, ensuring assembly surface smooth and without burr. (See table 3)

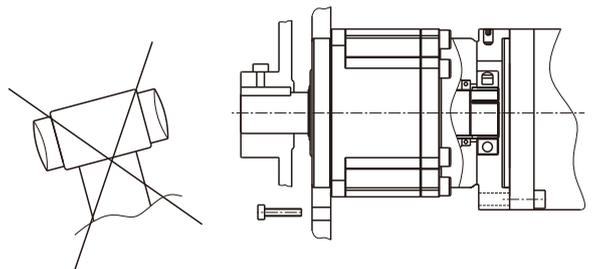
● Table 3

Reducer Combination Bolt	Fastening Torque	
	(N·m)	(kgf·cm)
M5	5.80	60
M6	9.80	100
M8	19.6	200
M10	39.2	400
M12	68.6	700
M16	16.8	1650

Connection to the Output Shaft

Cautions:

- 1、 When assemble a coupling, pulley, etc. onto the output shaft, make sure that excessive axial load not be given to the output shaft.
- 2、 In case of strongly hitting the shaft with a hammer, the shaft inlet or the inside of the reducer may be damaged, therefore it shall be prohibited.
- 3、 If the shaft or key of a coupling assembled is loosed, it may cause carbonization, so be careful when assembling.
- 4、 For assembling of a coupling, fix the key with a set bolt.
- 5、 Please adjust shaft centre carefully in connecting.



CATALOGUE



PRECISION HARMONIC REDUCER



CYCLOIDAL PIN WHEEL
PRECISION REDUCER



TRANSMISSION PLANETARY
GEAR MOTOR



SERVO DRIVER
BRUSHLESS DRIVER
INDUSTRIAL VEHICLE DRIVER
AC SPEED CONTROLLER



DC BRUSHLESS GEAR MOTOR



MOTOR ROLLER





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