

A MEMBER OF THE **ESTUR** GROUP

TRIO MOTION TECHNOLOGY SCARA ROBOT

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THE MOTION SPECIALIST

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	Developm	nent Tools	MOTION- i	X Advanced M	lotion Core	Network / T	Technologies
	Project Management	3D Visualisation	MOTION-iX Programming	64bit Precision	Up to 128 axis coordination control	EtherCAT	RTEX
Machine	SECURITY Project Encryption	6D Motion Scope	IEC61131	Scalable Motion Technologies	Complex Motion	ETHERNET/IP PROFIN	PROFINET
Automation Technology	SIMULATION	CAMGen	PLCopen	Kinematic SCARA Delta Cartesian	G-Code and HPGL	MODBUS TCP	DEVICENET
	Drive configuration	CAD2Motion	API - PC Application Development	Path Planning Look Ahead	Advanced Interpolation	CANOPEN	FUNCTIONAL SAFETY
	HMI Design	Program Libraries	ROBOTICS Programming	GEARING/CAM MOVELINK FLEXLINK	Registration Control	OPC UA	

Combining an advanced motion core with Trio's ease-of-use, Motion-iX offers performance and dependability of packaged solutions, from "The Motion Specialist", where motion is the core and not just a bolt-on capability. Motion-iX – a unified software engineering framework for machine development, that places the focus on optimising motion and complex kinematics, including robotics such as SCARA, to deliver truly optimal machine control performance.

Motion-iX includes development in IEC61131 and PLCopen, and boasts inverse kinematics

capabilities to truly coordinate all machine axes as one, including robots to maintain tight synchronisation or robots and machine as one. Virtualization allows simulation of the mechanics and motion to significantly reduce development and testing, delivering optimal control every time, by minimising machine cycle times.

Motion Perfect

Design, Develop, Test, Deploy and Secure



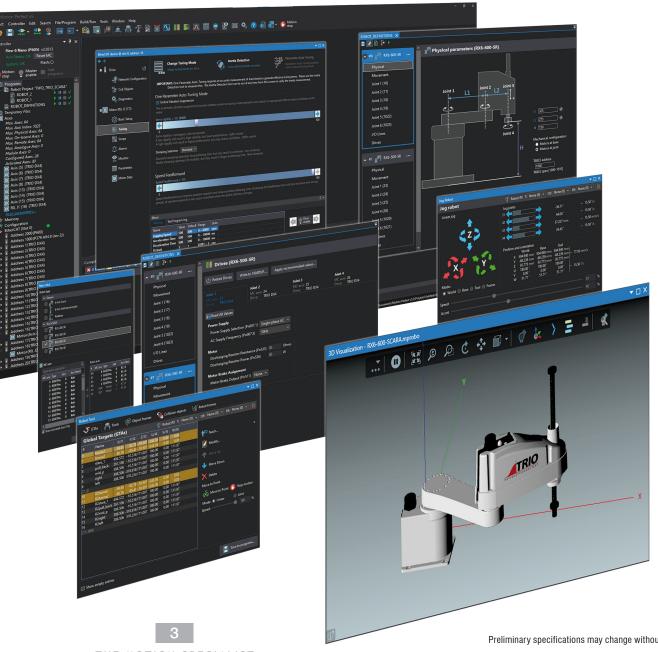
Built on Trio's Motion-iX core technology, *Motion* Perfect provides the user with an easy to understand interface for rapid application development, controller and drive configuration and monitoring of functions.

Motion Perfect includes access to IEC 61131 and PLCopen, advanced visualisation including a 3D oscilloscope and IP protection of your projects and the robotics solution; TrioRPS - the "Complete Automation Solution for Machine and Robot".



Trio RPS, brings robotics automation to everyone, with a great user experience and incredibly fast setup.

The Trio RPS is a sophisticated package of tools and software that can be adapted to different robot manufacturer's requirements, adding high value to your production line thanks to the combination of advanced motion control and industrial robotics.



SCARA D1000 – D1003 400mm - 700mm SCARA Robot

Why Interface when you can Integrate?

Using a traditional robot controller approach presents challenges of programming the interaction between a machine controller and the robot controller, and two separate systems to maintain.

An integrated solution with robot and machine control as one coordinated system, maximizes performance and simplifies the programming and future maintainability and extensibility of the system.

AT A GLANCE

- Trio SCARA package based on standard parts for simpler maintenance and offers standard cabinet install (no custom box required)
- ★ Applications specific integration, adaptation of the application is possible, including IO extension with our FlexSlice IO offer
- Motion is simpler to implement in the Trio software environment (which includes IEC61131) than many PLCs
- The Trio controller can be programmed to control more of the machine solution and integrate machine elements, including additional axes, simplifying the PLC hardware and project
- ★ Upstream Ethernet connection to the machine system / PLC (Ethernet/IP, Modbus TCP, Profinet IO)
- DX standard drives can be used for other machine axes, making spares and maintenance even simpler



Efficiency-Benefits



Integration Efficiency

Rapid application development of controller and robot configuration with TrioRPS within *Motion* Perfect.

Design Efficient

One system to program, simplifying development and any future production changes needed.

Performance Efficient

Tightly coupled actions between robot and machine axes improves process quality and perfomance.

Maintainance Efficient

Spares holding of the robot control unit is simplified by using standard servo drives and motors to minimize downtime and reduce spares value

RIC

MOTION TECHNOLC

True Robot and Machine Integration

One Scalable integrated solution



Machine and Robot Control



A choice of Trio EtherCAT *Motion Coordinators* Scalable to 128 axes of control





Multiple SCARA Robots Integrated With Your Machine

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Multiple machine and robot axes synchronised from one controller

MACHINE CONTROLLER

Responsible for the entire machine cycle and motion control.

Integrated robot path planning and coordination with machine axes.

TRIO DX4 DRIVE AXES FOR THE MACHINE

Common spares and service experience for robot and machine axes.

Tightly coupled motion between machine and SCARA.

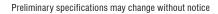
MULTIPLE INTEGRATED AXES

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Axes easily coordinated by the machine controller as part of the standard machines axes, making interactive processes simpler to implement.

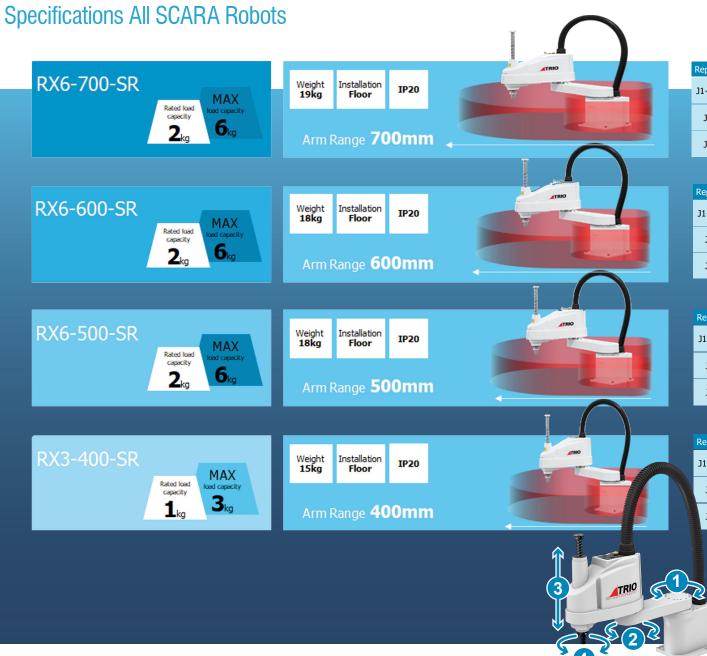
Your machine may only need one or two SCARA now, but how would you handle future expansion?

One Controller - Multiple Drives - Multiple SCARA.



Specifications All SCABA Bobot





Repeatability Range Speed 1 ±132° 375°/s J1+J2 ±0.025mm Complex Speed 7403mm/s 2 ±150° 588°/s J3 ±0.015mm 3 0~200mm 1100mm/s J4 ±0.01° 4 ±360° 2000°/s

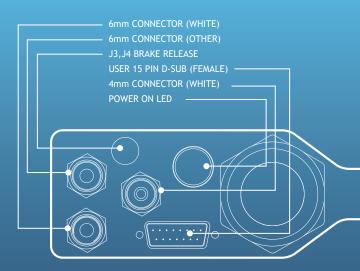
Repeata	bility	Rang	де	Speed		
J1+J2		Complex Speed				
10	2 ±150°	588°/s	7403mm/s			
J3	±0.015mm	3	0~200mm	110	0mm/s	
J4	±0.01°	4	±360°	20	00°/s	

Repeata	bility	Rang	e	Speed	
J1+J2		Complex Speed			
12	10.015	2 ±150° 588°/s	6094mm/s		
J3	±0.015mm	3	0~200mm	1100mm/s	
J4	±0.01°	4	±360°	20	00°/s

epeata	ability	Rang	je	Speed	
1+J2	±0.02mm	1	±132°	600°/s	Complex Speed
12			±141°	600°/s	5984mm/s
J3	±0.015mm	3	0~150mm	110	0mm/s
J4	±0.01°	4	±360°	20	00°/s

SCARA Connectivity

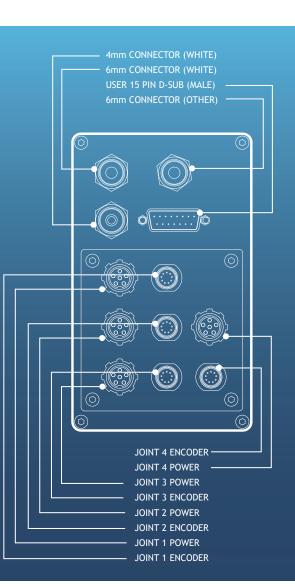




Connectivity

SCARA gives you the option to connect compressed air systems and electrical power via a 15 pin D-SUB connector for pneumatic and electrical end effectors which can be purchased separately.

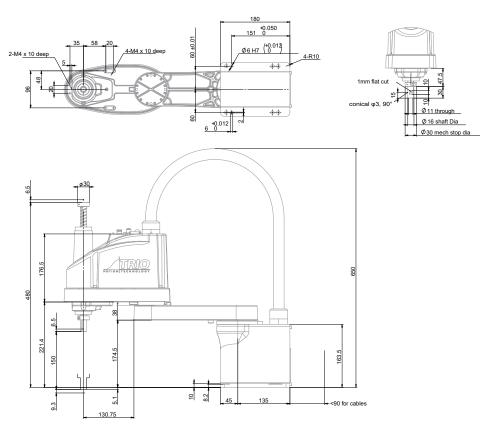
Each motor axis and encoder cable can be supplied in lengths of 1.5m, 5m, 10m, 15m and 20m allowing a range of positioning of the drives from the robot. Alternatively, encoder and motor cable kits are avilable for those customers wishing to make their own lengths.

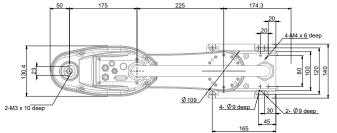


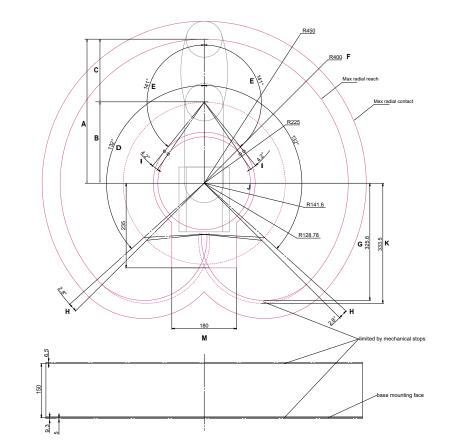


SCARA Specifications RX3-400-SR









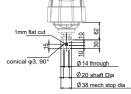
	STANDARD MODEL - RX3-		
	ltem	400-SR	
A	Length-Arm #1 & Arm #2 (mm)	400	н
в	Length-Arm #1 (mm)	225	1
С	Length-Arm #2 (mm)	175	J
D	Motion range-Joint #1 (°)	±132	к
E	Motion range -Joint #2 (°)	±141	м
F	Motion range (mm)	138.1	
G	Motion range of backside (mm)	325.6	

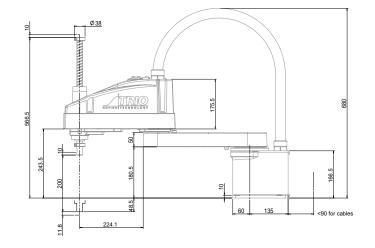
	STANDARD MODEL - RX3-				
	ltem	400-SR			
н	Mechanical stop position angle-Joint #1 (°)	2.8			
T	Mechanical stop position angle-Joint #2 (°)	4.2			
J	Mechanical stop position range (mm)	121.8			
К	Mechanical stop position range-backside (mm)	333.5			
М	Motion range (mm)	180			
	Maximum space (mm)	560			

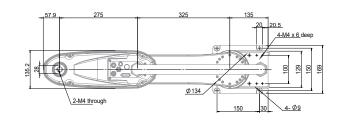
Specifications RX6-500-SR | RX6-600-SR | RX6-700-SR



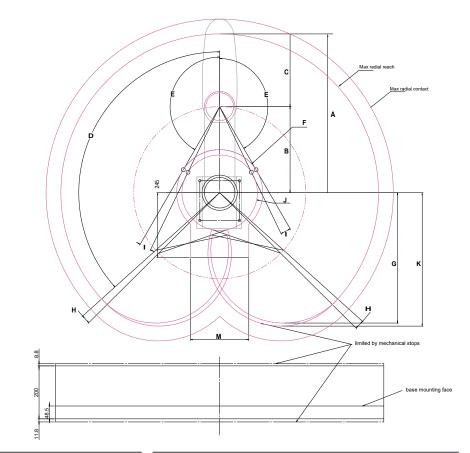
2-M4 x 10 deep 4-M4 x 10 deep 6 0 017 195 4-M4 x 10 deep 6 0 017 00 1 4-M4 x 10 deep 6 0 017 00 1 4-M4 x 10 deep 6 0 017 00 1 0 0 0 H7 (⁴0.012) 0 H7 (⁴0.012) 0 0 H7 (⁴0.012) 0 H7 (⁴0.0







	STANDARD MODEL - RX6-				
	Item	500-SR	600-SR	700-SR	
А	Length-Arm #1 & Arm #2 (mm)	500	600	700	
В	Length-Arm #1 (mm)	225	325	425	
С	Length-Arm #2 (mm)	275	275	275	
D	Motion range-Joint #1 (°)	±132	±132	±132	
Е	Motion range -Joint #2 (°)	±150	±150	±150	
F	Motion range (mm)	138.1	162.6	232	
G	Motion range of backside (mm)	425.6	492.5	559.4	



	STANDARD MODEL - RX6-					
	Item	500-SR	600-SR	700-S		
н	Mechanical stop position angle-Joint #1 (°)	2.8	2.8	2.8		
L	Mechanical stop position angle-Joint #2 (°)	4.2	4.2	4.2		
J	Mechanical stop position range (mm)	121.8	142.5	214		
Κ	Mechanical stop position range-backside (mm)	432	504	617.3		
М	Motion range (mm)	240	220	220		
	Maximum space (mm)	560	660	760		

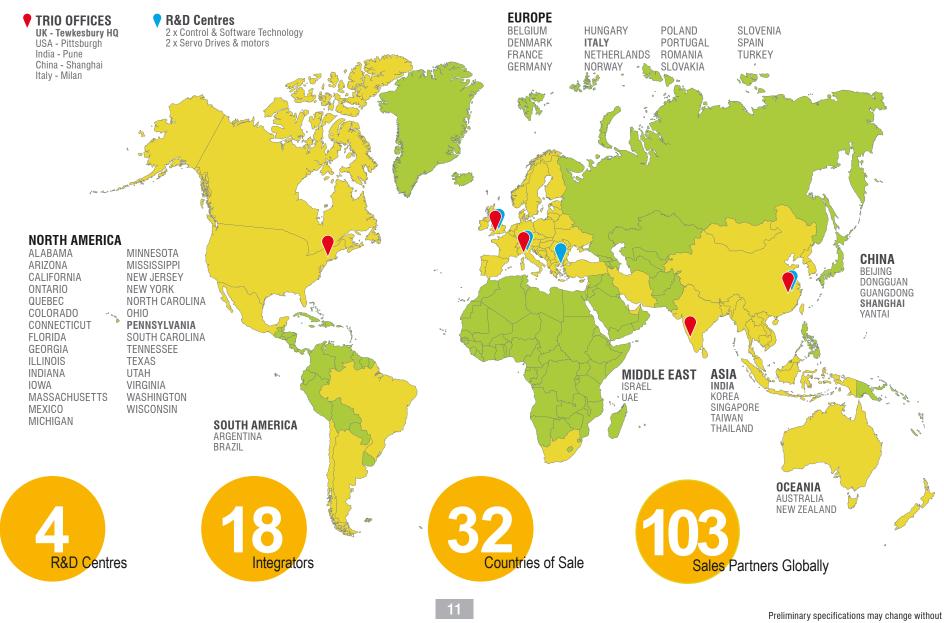
SCARA The Future is an integrated Machine





TRIO Worldwide Network







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TRIO MOTION TECHNOLOGY SCARA ROBOT

Trio Motion Technology specialises in advanced motion control as a core, providing a range of *Motion Coordinators*, drives and motors, expansion interfaces, IO modules and HMI's built on **Motion-iX** technologies and designed to enable the control of industrial machines with the minimum of external components.

In support of the Trio concept, we aim to offer the best technical support by telephone, email, our comprehensive website and training courses held throughout the year. Please look at our web site for details.

www.triomotion.com

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Version 1-SCARA Product brochure