

"Powerful & Compact" Robot for various manufacturing processes.

MC20/MC10L



MC20/MC10L

Robot specifications

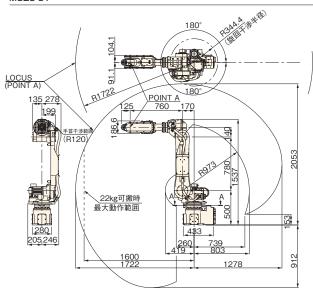
Item		Specifications	
Robot model		MC20-01	MC10L-01
Construction		Articulated construction	
Number of axes		6	
Drive system		AC servo system	
Max. operating area	J1	±3.14rad (±180°)	
	J2	+1.05~-2.53rad (+60~-145°)	
	J3	+4.22~-2.84rad (+242~-163°)	
	J4	±3.14rad (±180°)	
	J5	±2.42rad (±139°)	
	J6	±6.28rad (±360°)	
Max. speed	J1	2.96rad/s (170°/s)	2.62rad/s (150°/s)
	J2	2.96rad/s (170°/s)	
	J3	2.96rad/s (170°/s)	
	J4	6.28rad/s (360°/s)	
	J5	6.28rad/s (360°/s)	
	J6	10.5rad/s (600°/s)	
Payload*1		20 k g (22kg) 20kg(Max. 22kg)	10kg
Wrist torque	J4	49N•m	24.5N·m
	J5	49N•m	24.5N·m
	J6	23.5N·m	12N·m
Wrist moment of inertia*2	J4	1.6kg·m²	
	J5	1.6kg•m²	
	J6	0.8kg·m²	0.7kg·m²
Position repeat accuracy**3		±0.06mm	
Maximum working air pressure		0.49MPa (5.0kgfcm²) 0.49MPa (5.0kgf/cm²) or less	
Ambient temperature		0~45°C	
Installation		Floor mounted · Ceiling mounted	
Environmental resistance**4		IP65 Meets the IP65 standard (for dust and waterproofing)	
Robot mass		220kg	225kg

 $1[rad] = 180/\pi[^{\circ}], 1[N \cdot m] = 1/9.8[kgf \cdot m]$

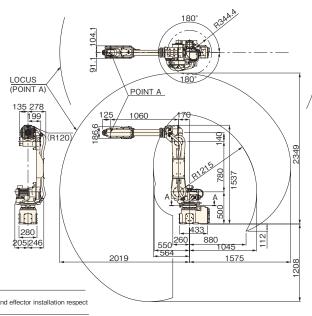
- **1 :This value varies from the installed position and the wrist load mass.
 **2 :Note that wrist moment of inertia varies depending on wrist load conditions.
 **3 :JIS B 8432 compliant.
- $\ensuremath{\,\%\xspace^{\,\cdot}}\xspace4$:Fluids that corrode the seal material, such as organic solvents, acids, alkalis, salts, and petroleum-based cutting fluids, cannot be used.

Exterior dimensions and operating envelope

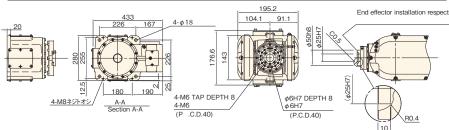
MC20-01



MC10L-01



Common Specification





URL: http://www.nachi-fujikoshi.co.jp

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